

# Three Talks about Robots

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For the last seminar of the academic year, we have three talks.

## Gait-based Control for Snake (Undulatory) Robots

Jinwoo Kim

## Contextual Multi-Objective Path Planning

Anna Nickelson.

## Autonomous underwater docking using flow state estimation and model predictive control

Rakesh Vivekanadan



FRIDAY  
Jun 16  
10-11AM

Rogers Hall 230  
FREE  
Refreshments Served

OSU Robotics  
[robotics.oregonstate.edu](http://robotics.oregonstate.edu)



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